

IN THE CLAIMS

Please amend the claims as follows:

- 1.-19. (Canceled)
20. (Previously Presented) The robot according to claim 36, wherein:
the holder and the lid have compatible shapes, and
the holder and the lid cover at least part of the opening when mounted together.
21. (Previously Presented) The robot according to claim 36, wherein the holder and
the lid are configured to cover the opening and to form a tight seal of the opening.
22. (Canceled)
23. (Previously Presented) The robot according to claim 36, the lid is configured to
be divided into sections through at least one direction.
24. (Canceled)
25. (Previously Presented) The robot according to claim 36, wherein at least one of
the removable sections of lid is configured to be compatible with the holder, and wherein the
holder and the lid are fixed in the opening to cover at least part of the opening.
26. (Previously Presented) The robot according to claim 25, wherein the holder and
the lid are configured to cover the opening tight-fittingly when mounted together.
27. (Canceled)
28. (Canceled)
29. (Previously Presented) An industrial robot comprising:
a control system including at least one cable set; and
a manipulator having an opening and a holder provided within said opening, said

holder having a collar with a U-shaped cross section that detachably connects to a section of an edge of said opening, said at least one cable set extending through said holder provided within said opening,

wherein the manipulator is provided with a pipe socket having the opening.

30. (Canceled)

31. (Previously Presented) The robot according to claim 29, wherein the holder is configured to be fixed with a hose clamp.

32. (Previously Presented) The robot according to claim 29, wherein said manipulator includes a lid configured to be detachably fixed to said edge.

33. (Previously Presented) The robot according to claim 32, wherein said lid has removable sections.

34. (Previously Presented) The robot according to claim 32, wherein:

said holder and said lid have compatible shapes, and

said holder and said lid cover at least part of said opening when mounted together.

35. (Previously Presented) The robot according to claim 32, wherein said holder and said lid are configured to cover said opening and to form a tight seal of said opening.

36. (Currently Amended) ~~The~~ An industrial robot according to claim 27 comprising:
a control system including at least one cable set; and
a manipulator having an opening and a holder provided within said opening, said
holder being detachably fixed along a section of an edge on a terminal end of said opening,
said at least one cable set extending through said holder provided within said opening,
wherein the manipulator is provided with a pipe socket having the opening, and

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wherein said manipulator includes a lid configured to be detachably fixed to said edge, said lid having removable sections.

37. (Previously Presented) The robot according to claim 36, wherein said removable sections have a breakable dividing line extending therebetween.

38. (Canceled)

39. (Canceled)

40. (Previously Presented) The robot according to claim 33, wherein said removable sections have a breakable dividing line extending therebetween.